

Starvation Mitigation Through Multi-Channel Coordination in CSMA Multi-hop Wireless Networks



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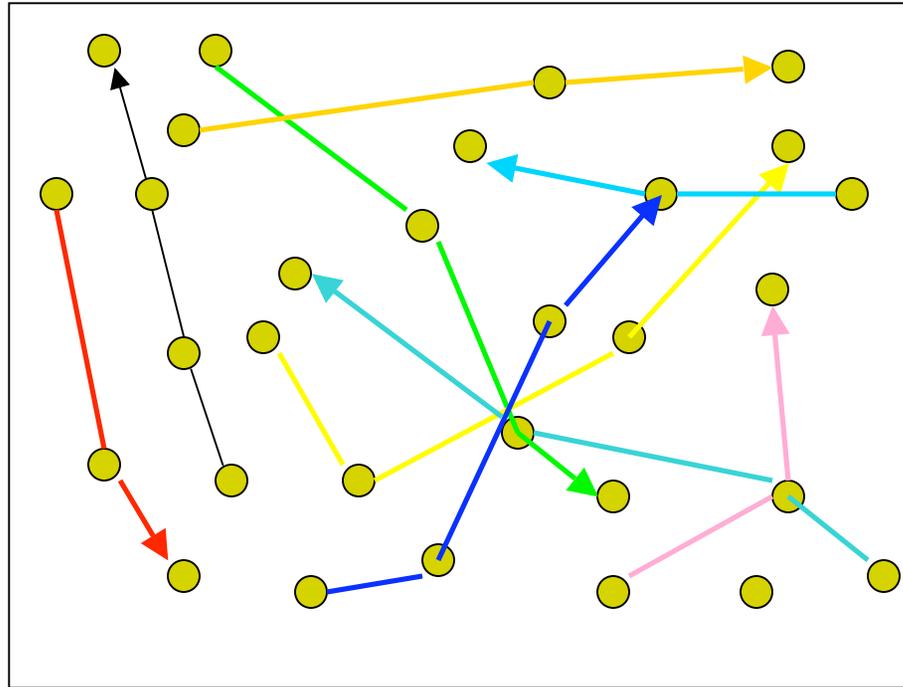
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Simulation in single-channel multi-hop CSMA networks



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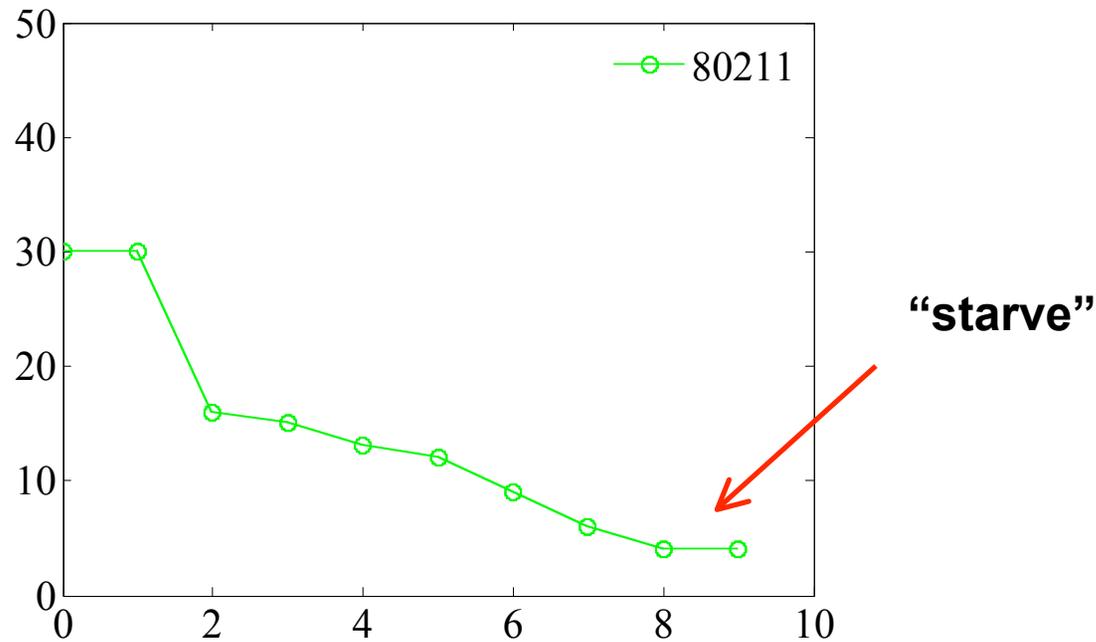


IEEE 802.11 networks, N_s 2, 50 nodes, 10 flows, 1m/s, 1000x1000m UDP load: 30 pkts/s

Starvation in single-channel multi-hop CSMA networks



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- Imbalanced throughput distribution in CSMA networks.

Using multi-channels to solve starvation



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- Solved with sufficient number of channels and radios, and global information.
- In practice, resources are limited, global information is not available.
- Some multi-channel protocols can efficiently increase aggregate throughput, given practical constraints.

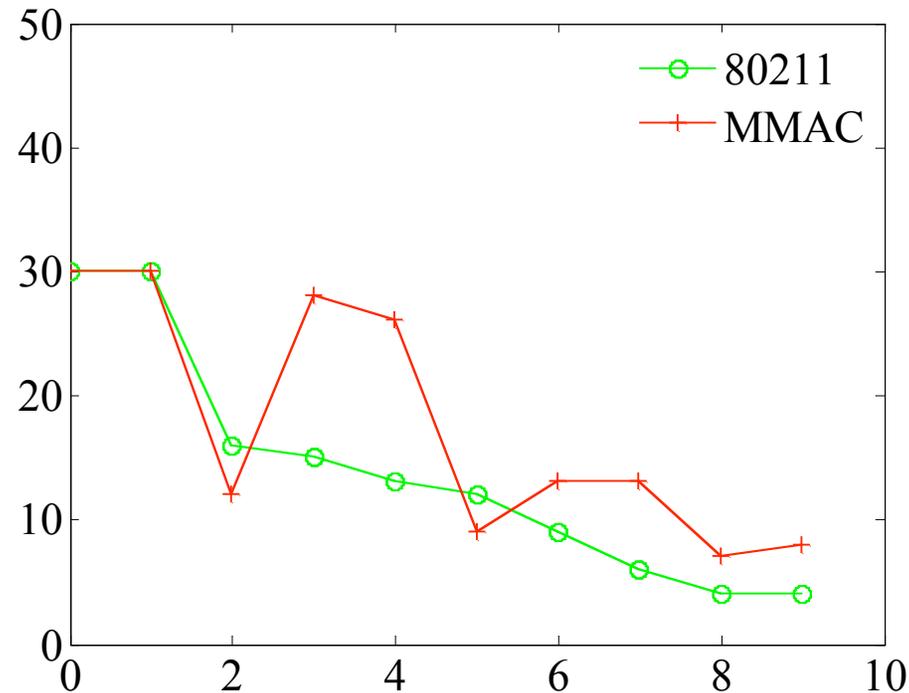
Multi-channel MAC (MMAC)

J. So and N. Vaidya. Multi-Channel MAC for Ad Hoc Networks: Handling Multi-Channel Hidden Terminals Using A Single Transceiver . In Proc. ACM MobiHoc, Tokyo, Japan, May 2004.

Using multi-channels to solve starvation, multi-hop flows



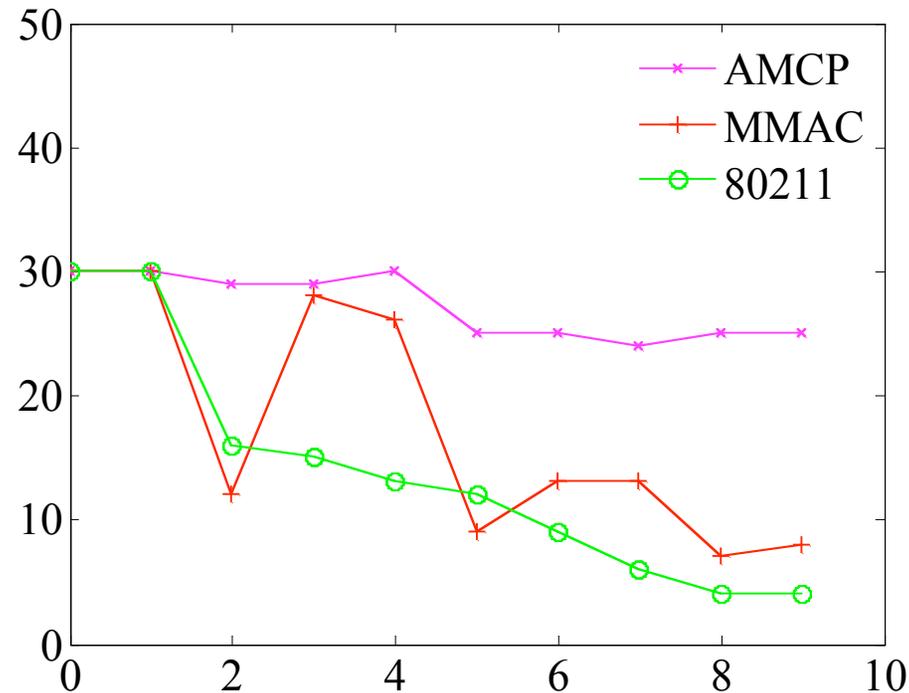
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- Multi-channel protocols do not necessarily address starvation.



Performance of our protocol



- Other protocols increase aggregate throughput.
- Our protocol significantly improves ***per-flow throughput.***

Our assumptions (system model)



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- Single radio, multiple channels.
 - Can only listen to or transmit on one channel.
 - Can only receive, or transmit, but not both.
- Channels are completely orthogonal.
- Multi-hop CSMA networks.

Challenges in solving starvation in multi-hop network



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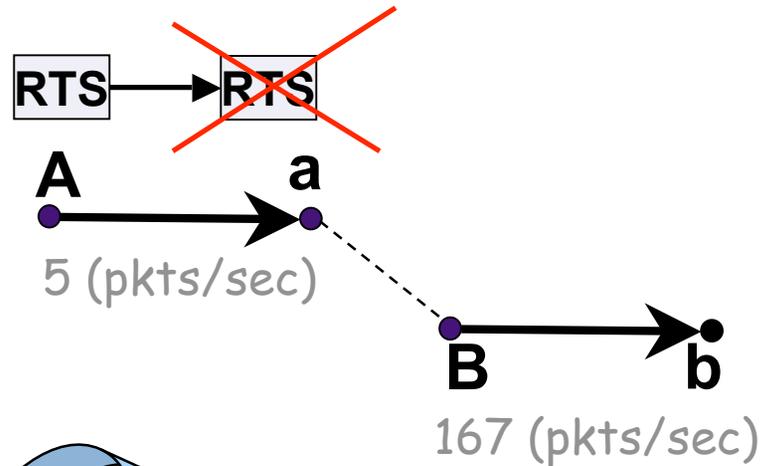
- Single channel starvation problem
 - Several transmissions can occur on one channel, thus inherit single-channel starvation problems.
- Multi-channel coordination problem
 - Separate transmissions to reduce interference.
 - Coordinate their transmission.
 - How to achieve these two goals.



Single-channel problems: asymmetric channel state

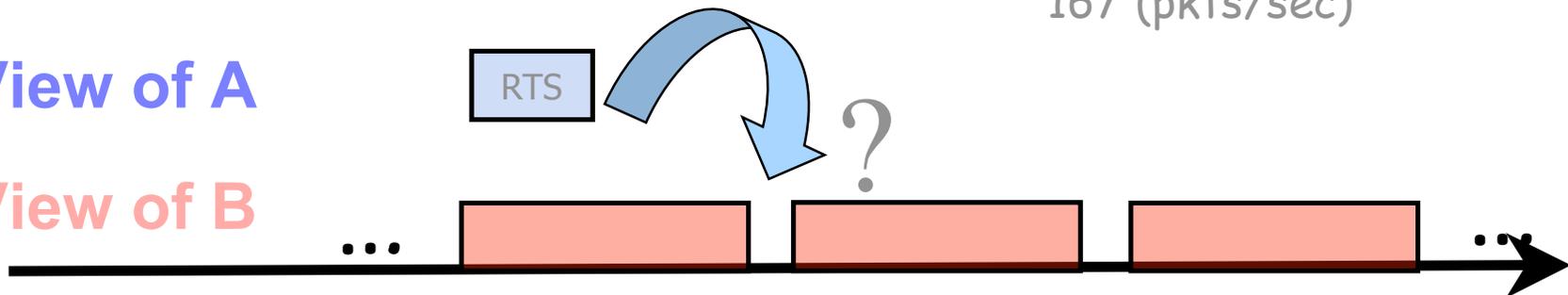
- Starvation due to asymmetric view of channel state.

Example



View of A

View of B



Long data packets make the interval even smaller.

Single-channel problems: uncoordinated transmissions

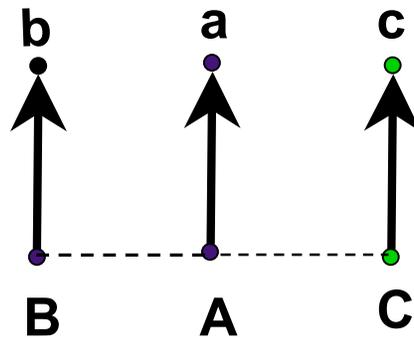


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- Starvation due to uncoordinated transmissions.

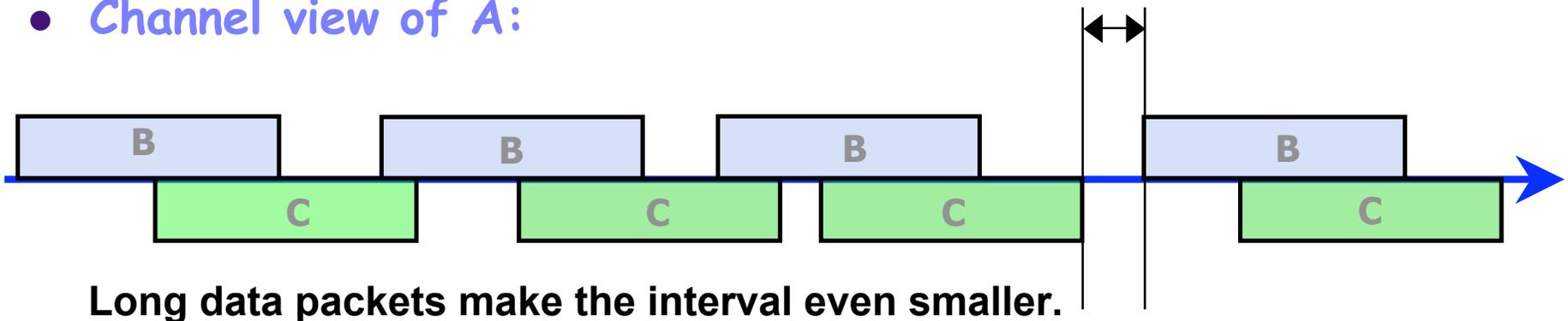
Example

170 2 170 pkts/sec



TxOp for A

- Channel view of A:



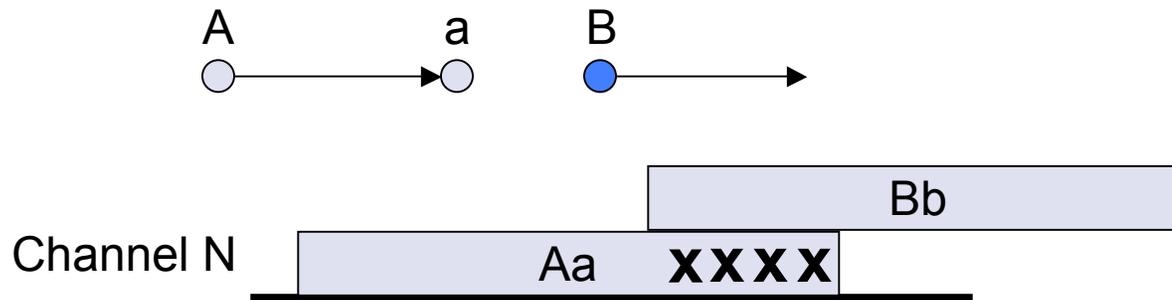
Long data packets make the interval even smaller.



Multi-channel coordination: missed channel reservation

- Channel reservation of one flow may not be heard by its neighbors on different channels.

Example



(First identified by *Junmin So et al, Mobihoc 04*)

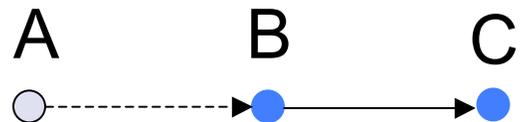
Multi-channel coordination: receiver on different channel



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- Receiver is missing (on a different channel)

Example



- Hard to synchronize channel hopping schedule.

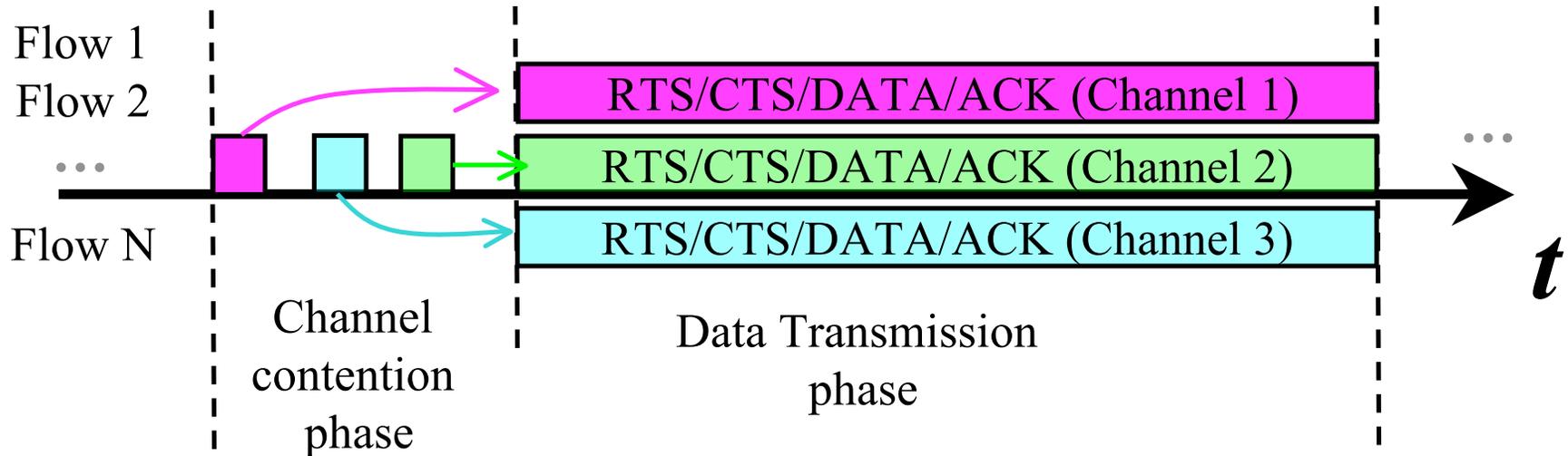
Challenges in solving all the problems



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MMAC (Junmin So, Mobihoc 2004)

Common time reference, infrastructure supported



Problems

- 1) Duration of negotiation phase
- 2) Receiver missing
- 3) Single channel starvation problems

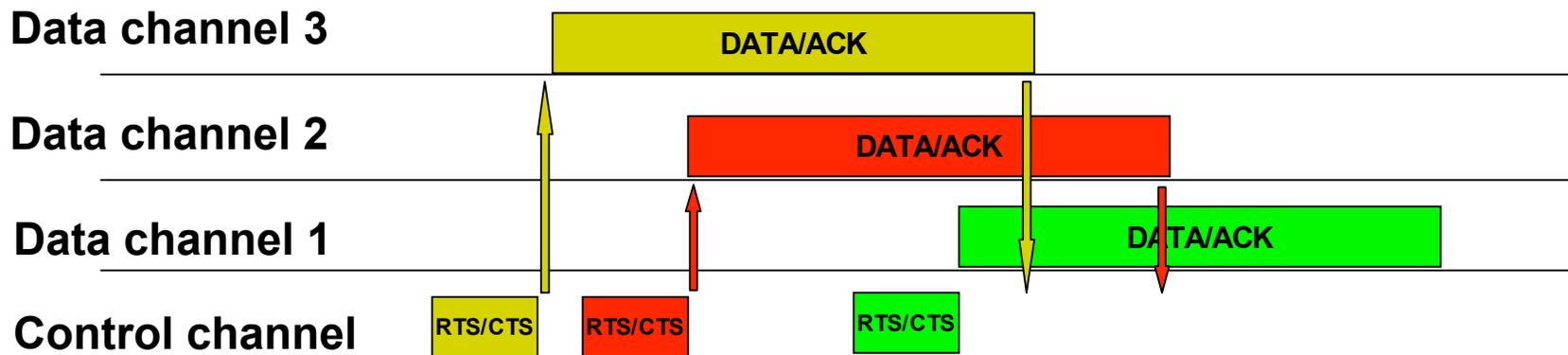
AMCP (Asynchronous Multi-channel Coordination Protocol)

general description



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- Asynchronous
- One common control channel, multiple data channels.
 - Separate control exchange from data transmission.
 - Provide a common frequency reference for nodes.

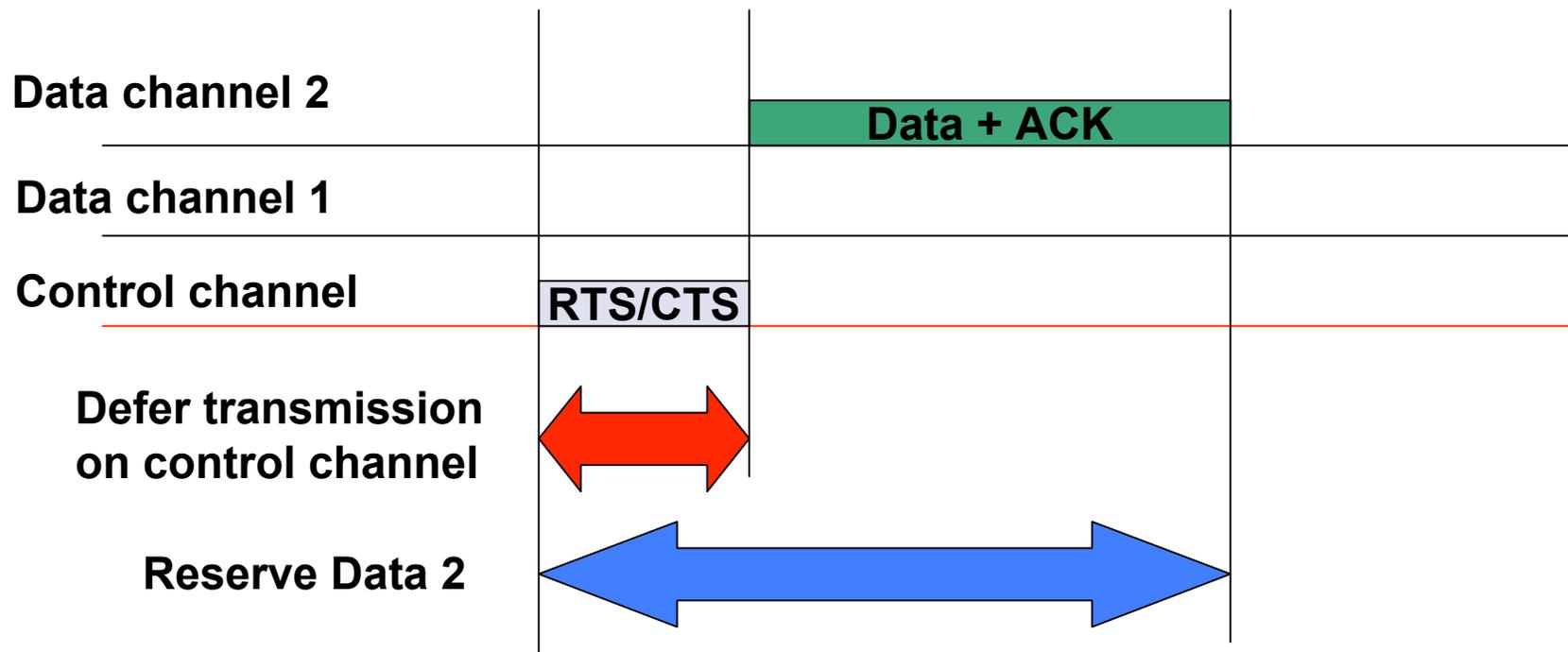


AMCP principle 1



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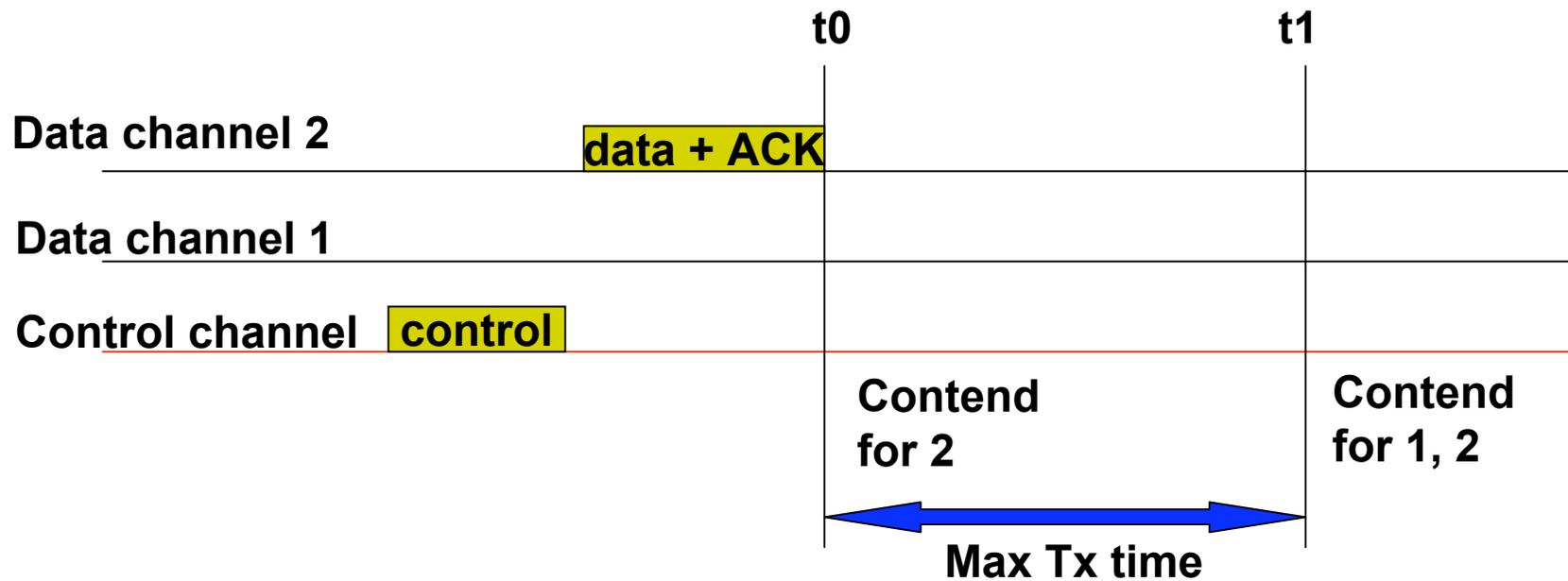
- Reserve common channel and data channel differently.
- Improve efficiency, avoid collision on data channels.



AMCP principle 2



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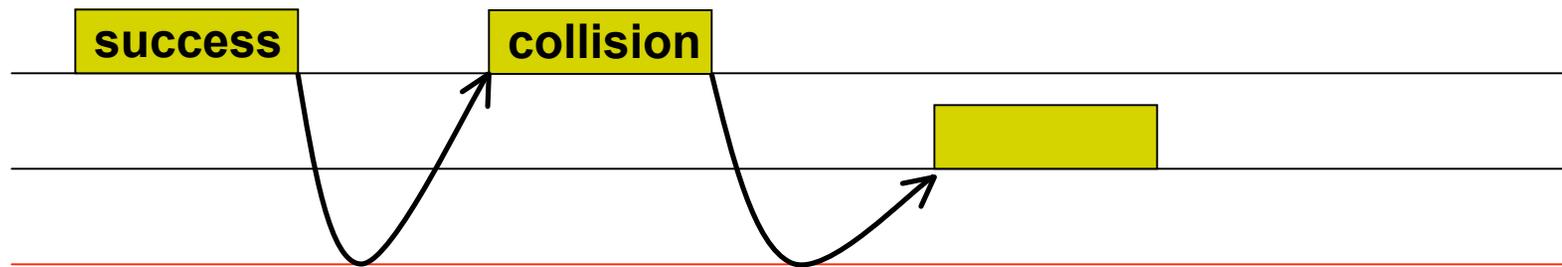


- Only contend for channels clear of traffic

AMCP principle 3



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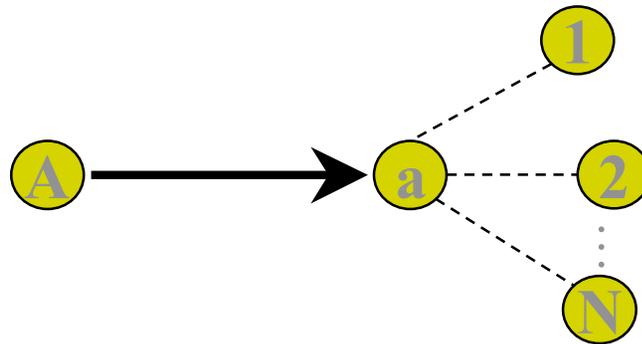
- **Self-learning channel hopping**
 - Stick to the channel given successful transmission
 - Contend for a different channel given collision

Lower throughput bound analysis step 1



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- Construct a worst-case low throughput scenario with N interferers: A cannot sense the activity of the interferers

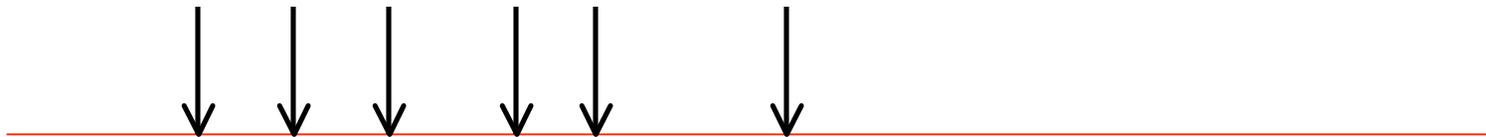


Lower throughput bound analysis step 2



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- Assume aggregate transmission attempt distribution is poisson.



- Compute conditional collision probability perceived by this flow.

$$p = 1 - e^{-\frac{2T_{RTS} + T_{CTS}}{T_{RTS} + T_{CTS} + T_{DATA}} N}$$

Lower throughput bound analysis step 3



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- Use our single-channel CSMA analytical model to compute the (minimum) throughput of this flow.

M. Garetto, J. Shi, and E. Knightly. Modeling Media Access in Embedded Two-Flow Topologies of Multi-hop Wireless Networks. In Proc. ACM MobiCom, Cologne, Germany, August 2005.

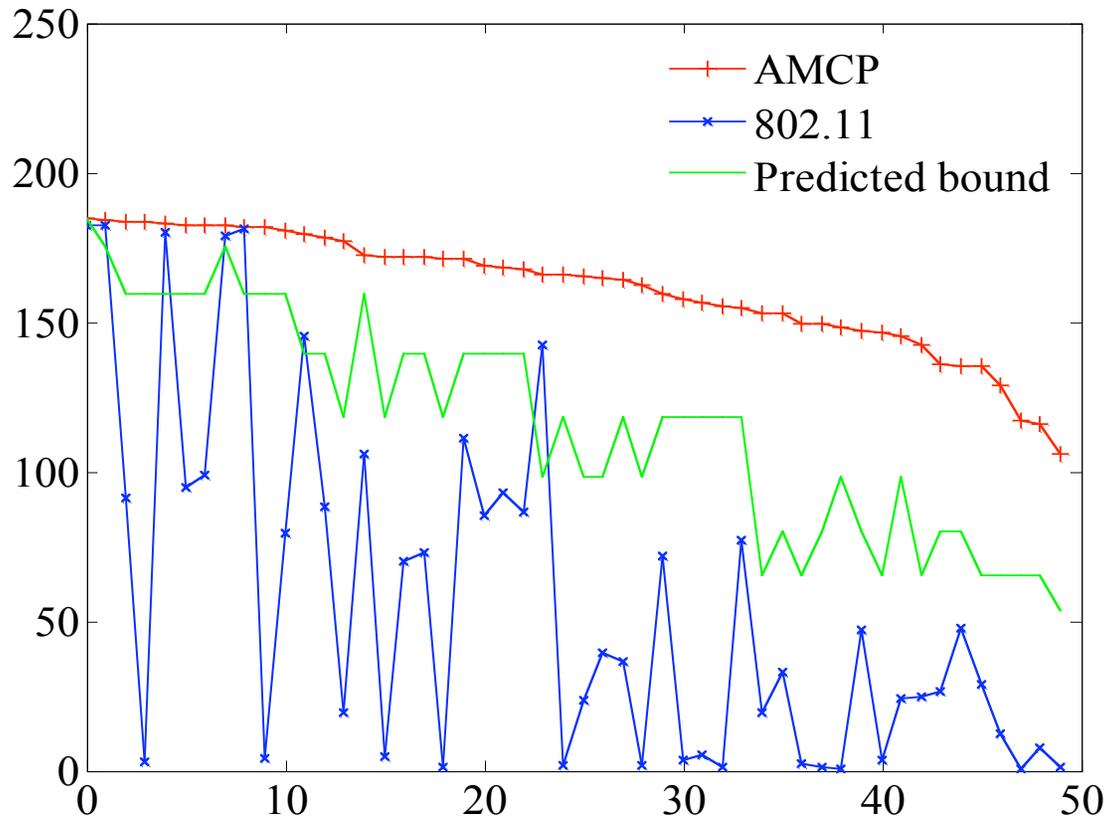
$$T_P(A) = \frac{[1 - \tau(B)]x}{\tau(B)\bar{T}_s + [1 - \tau(B)](1 - x)\sigma + [1 - \tau(B)]x\bar{T}_b}$$

Protocol Analysis (Arbitrary topology, single-hop flows)



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12 data channels, 100 nodes, 50 one-hop flows 1000m x 1000m area



Flows starve with 80211

Lower bound is much higher than 802.11

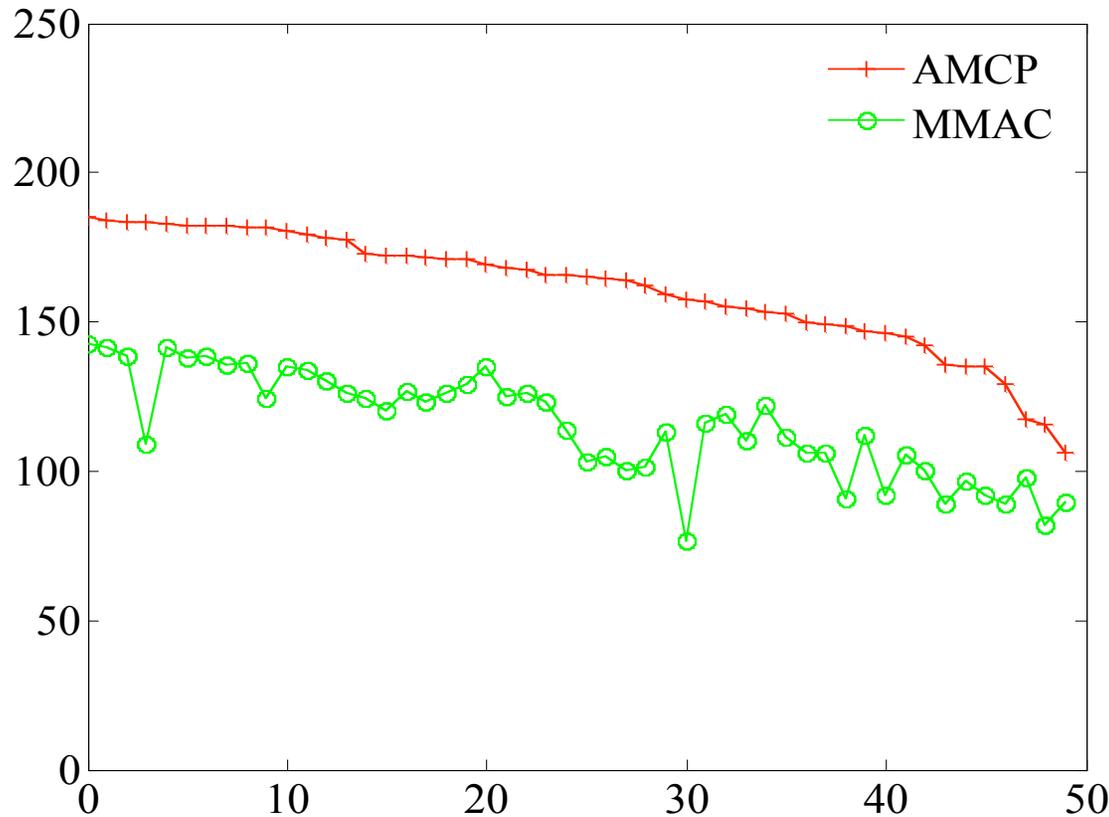
AMCP throughput higher than lower bound

Protocol Analysis (Arbitrary topology, single-hop flows)



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12 data channels, 100 nodes, 50 single-hop flows, 1000m x 1000m area



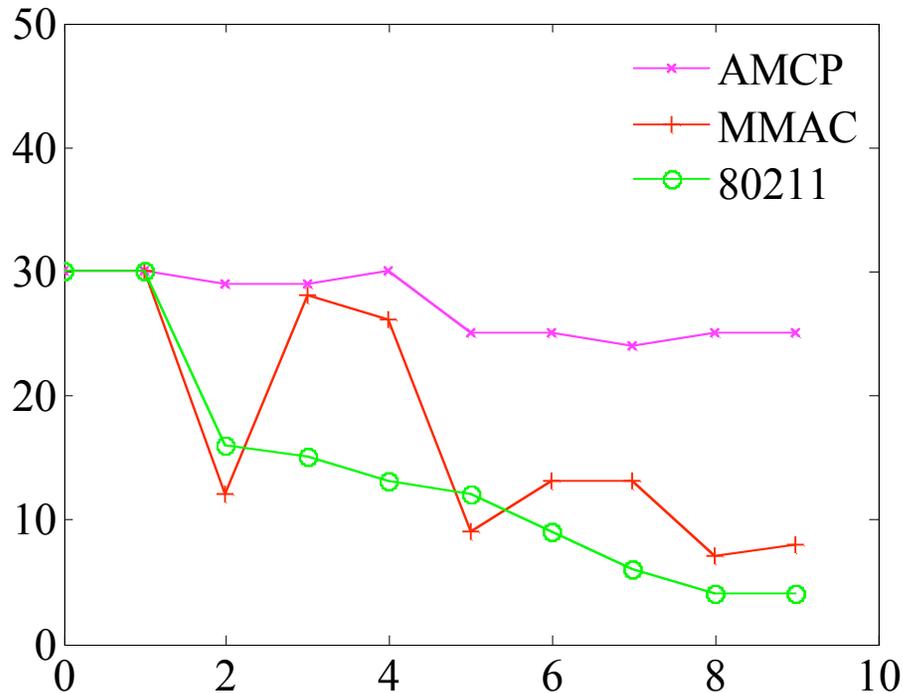
AMCP achieves higher throughput than MMAC

Protocol Analysis (multi-hop flows with mobility)



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50 nodes, 10 flows, 1m/s, UDP traffic: 30 pkts/s



**AMCP outperforms
802.11 and MMAC**



Summary of contributions

- Addressed both single-channel starvation and multi-channel coordination problems.
- AMCP significantly **increases per-flow throughput**.
- Derived approximate lower-bound.
- All these are achieved with single radio, without global synchronization.

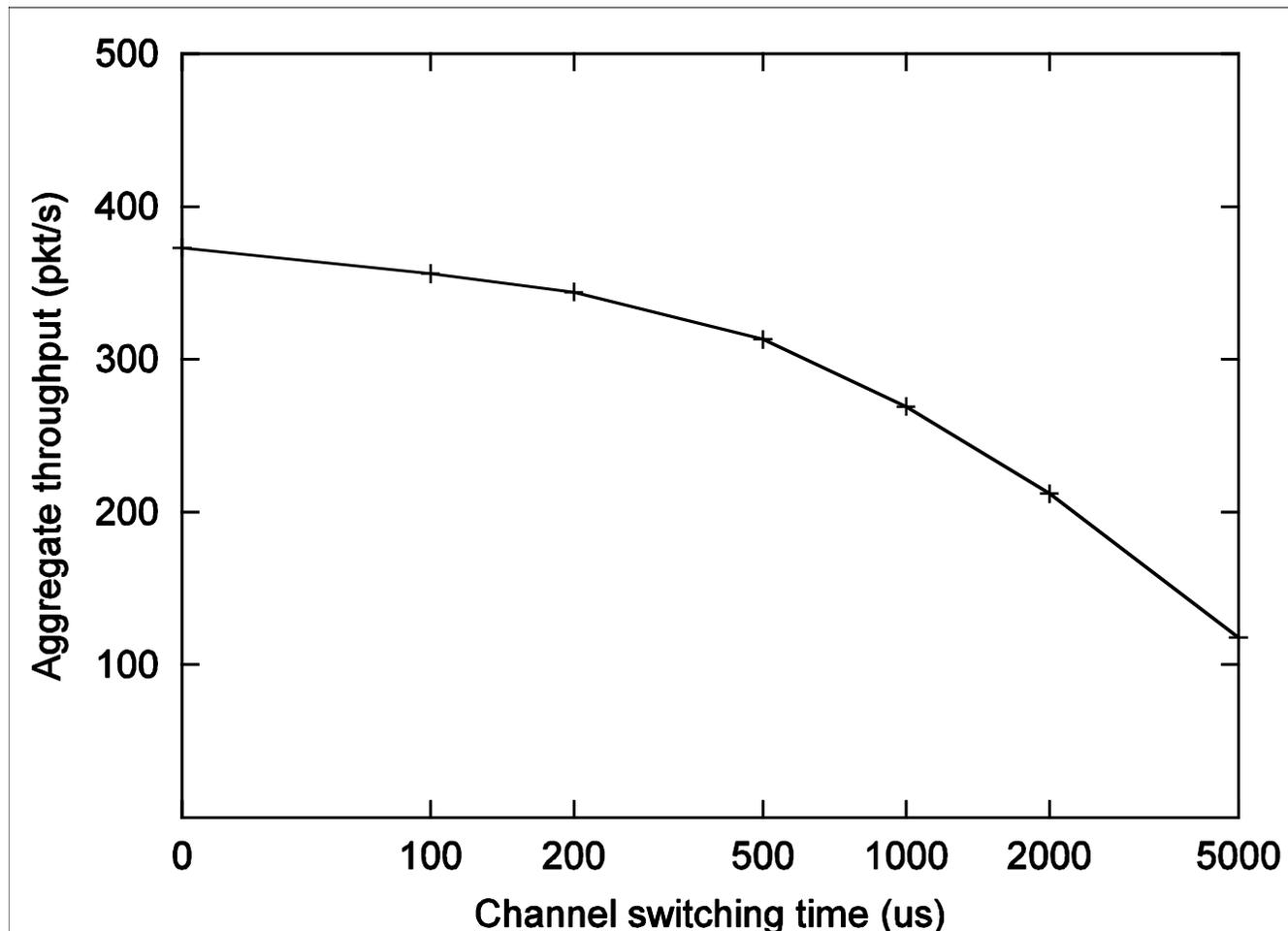


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Thank you !



Channel switching overhead

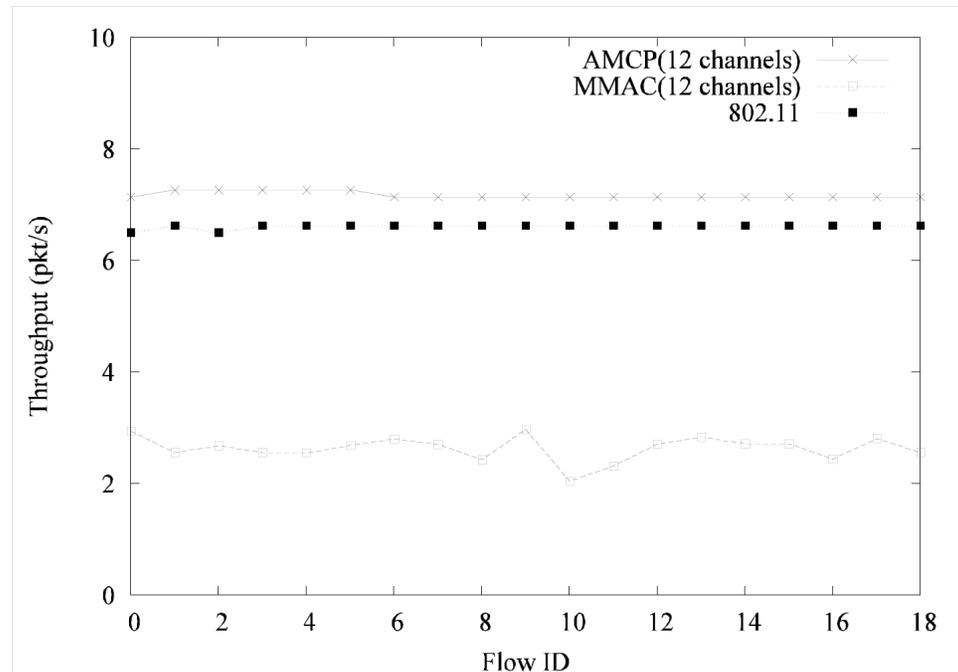
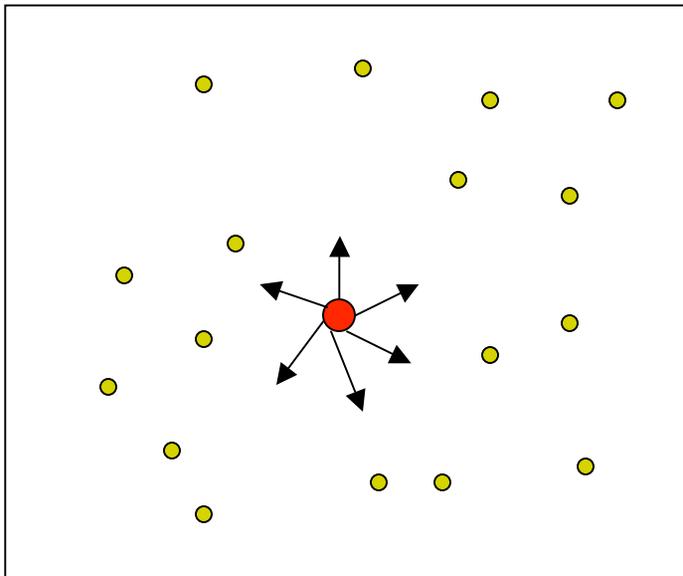


Protocol Analysis (Multi-hop flows, download scenario)



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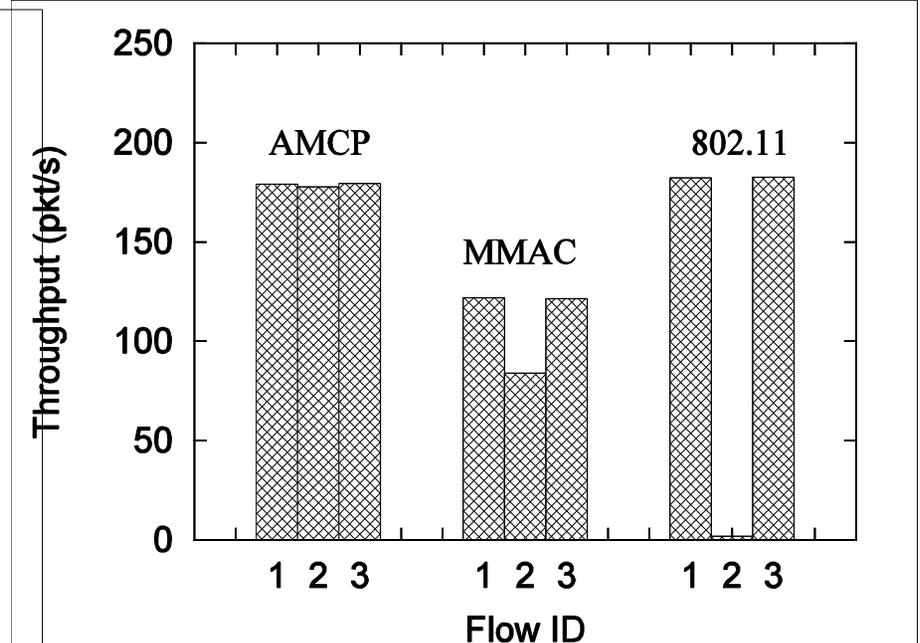
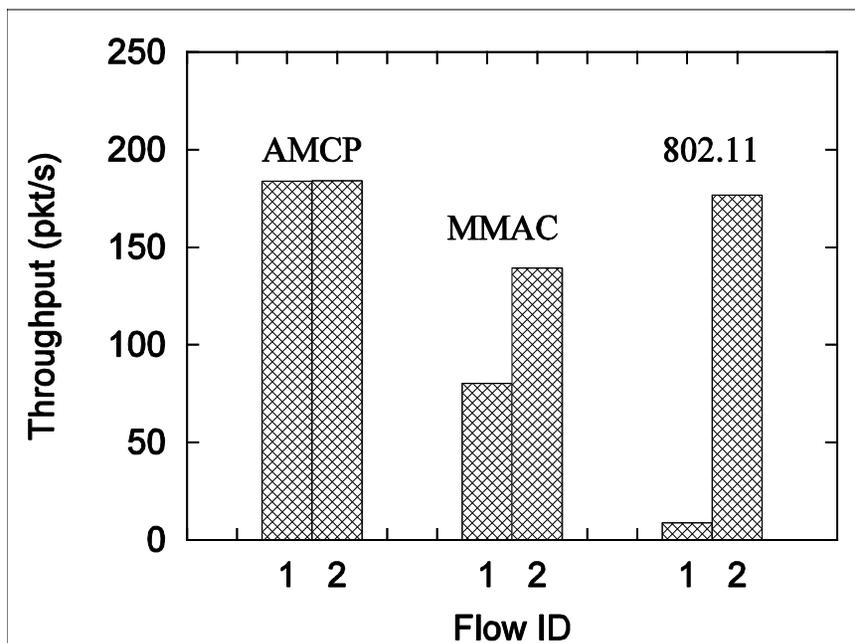
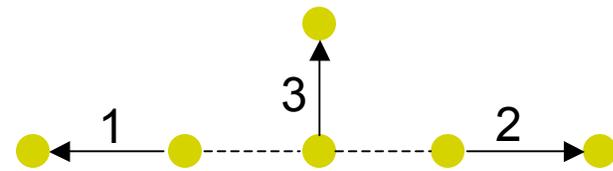
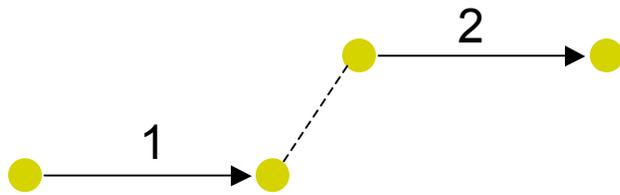
20 nodes, 19 flows, download traffic from the root



Protocol Analysis (starvation scenarios)



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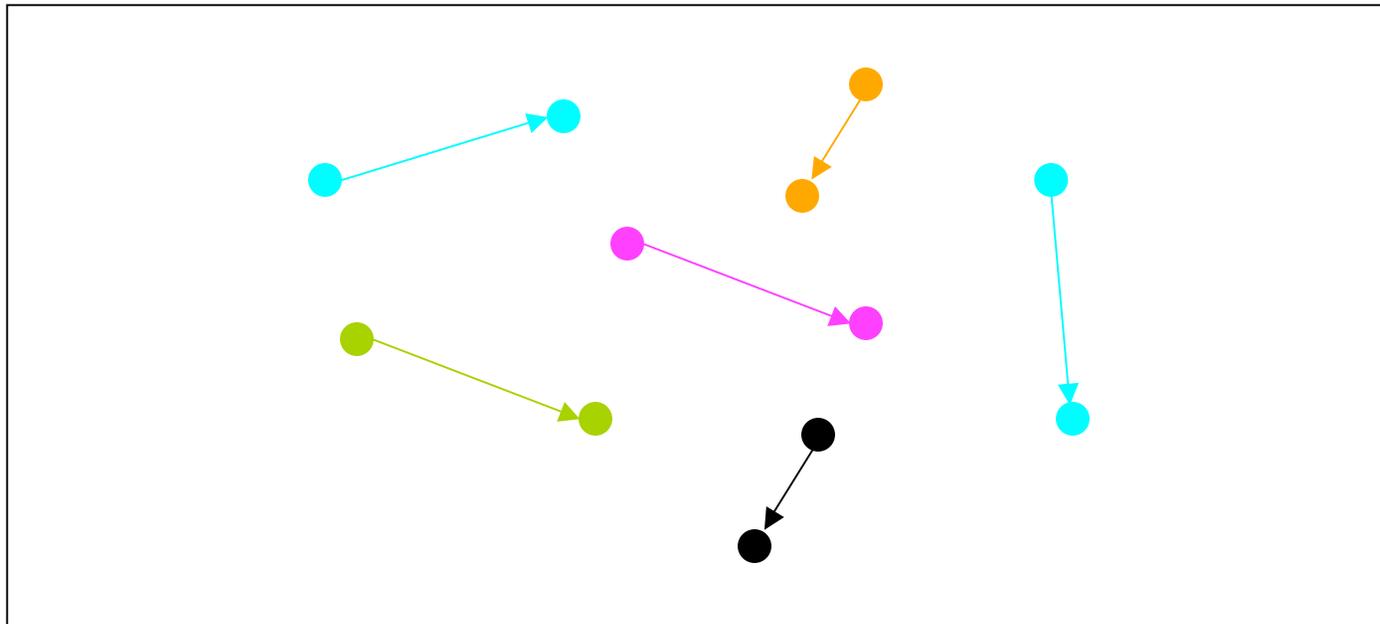


Two data channels, one control channel



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50 flows topology



Inefficiency due to channel switching constraints



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Some packets may be stuck in the queue due to in capabilities of swift channel switching

Example

